



# Robot Competitions Kick Innovation in Cognitive Systems and Robotics



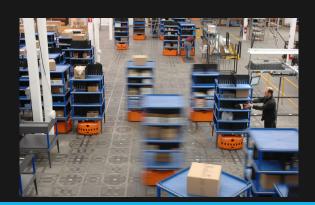


### Vision

# Robot competitions as a powerful mean to foster progress in Robotics R&D











Success Story	Robot Competition	
Google driverless car.	Sebastian Thrun's	
	Stanford team won	
	the DARPA Grand	
	Challenge 2005	
Kiva Systems revolutionized	One of company	
automation by using hundreds of	founders, Raffaello	
mobile robots for storing, moving	d'Andrea, was a	
and sorting inventory. On March	former participant	
19, 2012, Kiva Systems was	and winner of	
acquired by Amazon for USD 775	RoboCupSoccer's	
Million.	Small Size League.	
During the rescue operations in	Prof. Tadokoro is a	
the Fukushima-Daiichi Nuclear	former RoboCup	
<b>Power Plant</b> , no other robot but	Trustee, and leader	
<b>Quince</b> could go up to the 2nd -	of a team which	
5th floors in the nuclear reactor	participated with	
buildings.	Quince in	
	RoboCupRescue.	
Aldebaran Robotics' NAO robot	NAO won the	, M
	RoboCup 2007 Open	
	Call for a Stadard	
	Platform and became	
	the RoboCupSoccer	
	Standard Platform	and the same of th
	League robot that	
	replaced the former	
	Four Legged League	
	SONY AIBO robot	
	dog.	



# RoCKIn's competition led innovation

- A catalyst for smarter, more dependable robots
- Focus on cognitive skills and networked robots
- Will develop standardised testbeds and benchmarks that will streamline R&D for the future



#### The consortium







Hochschule Bonn-Rhein-Sieg





POLITECNICO DI MILANO

**INNO**CENTIVE "

#### **Advisory Board Members:**

Adam Jacoff, NIST, USA
Bill Smart, Oregon State University, USA
Bruno Siciliano, University of Naples Federico II, Italy
Jon Agirre Ibarbia, Tecnalia, Spain
Manuela Veloso, Carnegie-Mellon University, USA
Oskar von Stryk, Technical University of Darmstadt, Germany
XiaoPina Chen, University of Science and Technology of China, China

#### **Experts Board:**

Alessandro Saffiotti, Örebro University, Sweden Herman Bruyninckx, University of Leuven, Belgium Tijn van der Zant, University of Groningen, The Netherlands



### RoCKIn@Work

- Innovative robot applications in industry that:
  - Work interactively with humans
  - Have reduced initial programming requirements
  - Have enhanced physics simulation capabilities
- Contribute to the continued commercial competitiveness of European industry







### RoCKIn@Home

- Socially beneficial domestic service robots that
  - Have enhanced networking and cognitive abilities
  - Support the impaired and the elderly
- Contribute to an improved quality of life for the population of Europe







# RoCKIn@Work

**IROS 2012 Robot Competition** 

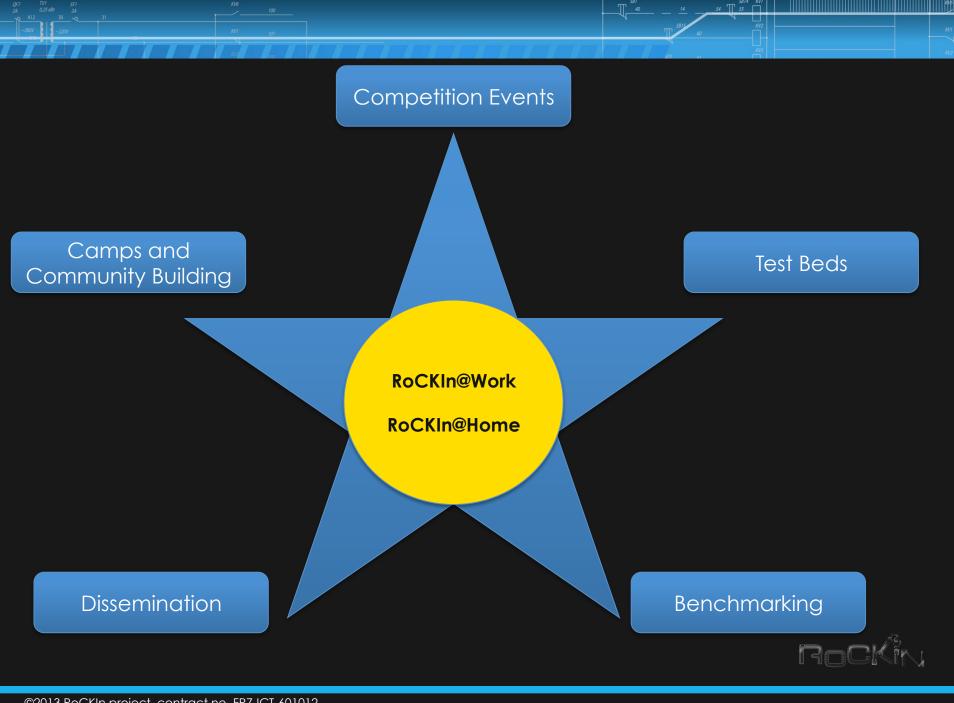


# RoCKIn@Home

#### RoboCup@Home 2012 Winner Team







### Camps and related events

- RoCKIn Kickoff Camp (2013)
  - will introduce potential participants to the RoCKIn project with the ultimate aim of facilitating the entry of new teams into RoCKIn@Home and RoCKIn@Work.
  - It will involve lectures, attending and evaluating parts of RoboCup@Home and RoboCup@Work, and participation in the RoboCup symposium.
- June 28th to July 1st during RoboCup2013, Eindhoven
- RoCKIn provides travel and accommodation support, and access to the RoboCup venue, symposium and an exclusive social event for the selected candidates.



### Camps and related events

#### RoCKIn Camp

- Planned for 2014
- Small groups working to together to build upon 2013 introductory event
- Aim is to educate, advance current tech and develop robots appropriate for RoCKIn competitive events

#### RoCKIn Field Exercise

- Planned for 2015
- Supports the final stage of team development
- Opportunity to test creations in a real world situation

#### Forums and workshops



# Competition events

- 2014:
  - Planned for a time window between March and May, place TBD

- · 2015:
  - Planned for European Robotics Week, Lisbon, end of November



### The consortium













POLITECNICO DI MILANO

**INNO**CENTIVE®

- Find out more:
  - http://rockinrobotchallenge.eu
  - Twitter: @RoCKInchallenge
  - Facebook: search 'RoCKiN'



